ZHENFEI YANG

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EDUCATION

Hong Kong University of Science and Technology

Sep. 2014-Aug. 2016

MPhil. in Electronic and Computer Engineering, Deportment of ECE

Supervisor: Shaojie Shen

Harbin Institute of Technology

Sep. 2010-Aug. 2014

BEng. in Computer Science and Technology, Honors School

GPA - 87.0/100 Rank 3/18

PUBLICATIONS

Self-calibrating Multi-camera Visual-Inertial Fusion for Autonomous MAVs

Intl. Conf. on Intell. Robots and Syst. (IROS)

Oct. 2016

· Zhenfei Yang, Tianbo Liu, and Shaojie Shen

Monocular Visual-Inertial State Estimation with Online Initialization and Camera-IMU Extrinsic Calibration

Trans. on Autom. Sci. and Engineering (T-ASE)

Apr. 2016

· Zhenfei Yang and Shaojie Shen

Monocular Visual-Inertial Fusion with Online Initialization and Camera-IMU Calibration Intl. Sym. on Safty, Security, and Rescure Robotics (SSRR) Oct. 2015

· Zhenfei Yang and Shaojie Shen

AWARDS

· First Prize, International Aerial Robotics Competition (IARC)

Nov. 2015

- · Best Theoretical Paper Award, Intl. Sym. on Safty, Security, and Rescure Robotics (SSRR) Oct. 2015
- · Silver Prize, ACM/ICPC Asia regional Changchun onsite

Oct. 2012

· Bronze Prize, ACM/ICPC Asia regional Jinhua onsite

Oct. 2012

WORKING EXPERIENCE

DJI Technology

Feb. 2014-Aug. 2014

Visual Computing Group

Project: Structure from Motion. Taking the video captured by a quadrotor as input, reconstruct the observed scene.

Main technique: Both the sparse landmarks and the poses of the quadrotor are estimated using feature-based sparse bundle adjustment. Given the accurate pose estimation, the sparse point cloud is densified through propagating the feature correspondences from texture-rich regions to texture-less regions.

Microsoft Research Asia

Jun. 2013-Sep. 2013

Internet Graphics Group

Project: TextFlow. After mining topics of bing news, use modified Stacked Graph to visualize the development progress.

Main work: Optimize the layout algorithm of the visualization module and redesign the structure for further research.